# Time-Cost Trade-offs of Pipelined Dataflow Applications

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- Cloud computing promises on demand resources
- Different types of computing resources are available
- Arbitrary speedups are in principle possible
- The catch is that you have to pay for resources used
- The problem becomes a **tradeoff** between the **runtime** of an application and **cost** of executing it

In this presentation, we show that the **pipelined dataflow abstraction** is good for expressing this tradeoff because runtime is "easy" to predict. We use a particular imaging application to examplify the technique.

# Feature Extraction from Histopathological Slides



**Biopsy slides** 

Non-blank patch Preprocess



SuperPixel

segmentation



LBP feature extraction

- $\bullet$  Varying sizes in the order of 100k  $\times$  100k pixels.
- Aperio Format with thumbnail (about 1GB/file, 24GB uncompressed)
- Available public repository (TCGA) with 1000s of participants samples
  - 3 slides per patients.
- Can be used to predict whether the biopsy is cancerous
- Will consider two instances: twoparticipants (2 participants) and allslides (42 participants)

## 1 Introduction

## Predicting Runtime of Pipelined Dataflow Application

## 3 A Flowshop Problem

### Time-Cost Tradeoff

## 5 Conclusion

# Pipelined workflow



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Time-Cost in Pipelined Applications

In a pipelined system what matters is the steady state! The throughput is given by the most loaded node.

# Runtime in a (simple) pipelined dataflow model

#### Model

- An application of M stages
- J identical jobs
- Stage *i* processes a job in *p<sub>i</sub>*

## One-to-one mapping

- With one processor per stage
- The execution is constrained by the slowest stage
- Period  $\mathcal{P} = \max_i p_i$
- Throughput  $T = \frac{1}{\mathcal{P}}$



### Replication

It is possible in some application to replicate some stages to increase the throughput

- If stage i is replicated  $r_i$  times
- *i* processes at a rate  $\tau_i = \frac{r_i}{p_i}$
- Throughput  $T = max_i\tau_i$
- Period  $\mathcal{P} = \frac{1}{T}$

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### Heterogeneity

It is possible in some application to replicate on different systems.

- If stage *i* is replicated on a CPU and a GPU
- *i* processes at a rate  $\tau_i = \frac{1}{p_i^{cpu}} + \frac{1}{p_i^{gpu}}$

• Throughput 
$$T = max_i \tau_i$$

• Period 
$$\mathcal{P} = \frac{1}{T}$$

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$$T = max_i \tau_i$$

• Period 
$$\mathcal{P} = \frac{1}{T}$$

# These two techniques combine !

# Experimental settings and model calibration

#### Machine

- 32-node cluster
- Two Xeon E5520 (quad core)
- An NVIDIA C2050
- DDR4x Infiniband

### Software

- g++ 4.8.1
- mvapich2 2.2
- DataCutter (dcmpi)
- Openslide 3.4.1
- gSLIC
- nvcc 7.0.27

### Tile prediction

based on thumbnail:



## Model Calibration

				Estimated	Estimated
Slide	Filesize	e Width	Height	Total Tiles	Valid Tiles
TCGA-BH-A18V-01A-01-TSA	432.93ME	98,631	33,244	225	78
TCGA-BH-A18J-01A-01-TSA	322.01ME	112,037	29,845	224	75
ImAn:					
CPU / GPU	Proc. Ti	me Loc	al $\tau_{IA}$	Average $\tau_{IA}$	Speedup
NVIDIA Tesla C2050	447.41	s 2.924	M px/s		
	422.03	s 2.981	M px/s	2.953M px/s	1
Intel Xeon E5520 (7 cores)	399.11	s 3.278	M px/s		
	378 83	- 3 3 2 1	M ny/e	3 200M my/c	1 117

# A first log



1 Reader. 3 GPUs. Two Patients. Natural ordering. (Eventually ImAn idles because too many White are read.)

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The Valid tiles are more computationally expensive than the White ones. Valid first should work fine!

# Valid First does not always work



(The system has bounded memory and eventually Reader stalls.)

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Deciding which job to process next in its simplest form is a Flowshop problem.

#### Model

- M stages
- J jobs
- job j in stage i takes time  $p_{i,j}$
- Order the job to minimize the makespan

#### **Bad News**

- NP-Complete in this form
- That is actually an abstraction of the real problem

Since you have categories of jobs, the  $p_{i,j}$  matrix is actually low rank. That helped in R || Cmax. Maybe it helps here?

## Insight

We have:

- C categories of jobs
- J<sub>c</sub> jobs in category c
- J<sub>c</sub> are large numbers

Sounds like something cyclic should work

## Algorithm

Build k batches with  $s_c = \frac{J_c}{k}$  jobs of category c

# Asymptotic optimality

Each batch can be seen as a meta job in a one-to-one mapping. When k goes to infinity, the makespan of the flowshop problem converges to the optimal value of the pipelined scheduling problem. So with lots of jobs, performance is good.

# **Dismissed Constraints**

### Divisibility

The number of jobs might be prime, but rational approximation works just fine.

### Heterogeneity

Called hybrid problem in the flowshop world. Heterogeneous just makes different *p*<sub>*i*,*j*</sub>.

#### Onlineness

Non-clairvoyance can be solved with random ordering.

#### Low-Rank

Categories and low-rank are slightly different. (low rank admits linear combination of categories.) Low-rank can be solved by some weighted interleave schedule

## Communication

Often modeled as an additional stage of processing.

## Blocking Writes

As long as one batch does not saturate memory, pipelining will happen gracefully.

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# In practice



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#### Time

#### Parameters:

- W white tiles
- V valid tiles
- r CPU Reader at a rate  $\tau_{Read}^{CPU}$
- c CPU ImAn at rate  $\tau_{ImAn}^{CPU}$

• g GPU ImAn at rate  $\tau_{ImAn}^{GPU}$ Prediction:

• 
$$\tau_{Read} = r \tau_{Read}^{CPU}$$
  
•  $\tau_{ImAn} = c \tau_{ImAn}^{CPU} + g \tau_{ImAn}^{GPU}$   
•  $C_{max} = \max(\frac{W+V}{\tau_{Read}}, \frac{V}{\tau_{ImAn}})$ 

#### Cost

Amazon EC2 charges per hour (MS Azure charges per minute) So the charge is  $\left\lceil \frac{C_{max}}{3600} \right\rceil ((r+c) * C_c + g * C_g)$ 

## What you can get

In EC2, you can get a cg1 instance with 2 NVIDIA M2050 and 8 Xeon core for \$2.1 per hour. For the reader, you can use a c1.medium that gives a Xeon core for \$0.13 per hour.

# $(1 + \epsilon)$ -approximation of Time-Cost

#### Cost under time constraint

If you set a cap T on time, then you obtain bounds

•  $\tau_{Read} \ge \frac{W+V}{C_{max}}$ • and  $\tau_{ImAn} \ge \frac{V}{C_{max}}$ So: •  $r\tau_{Read}^{c1} \ge \frac{W+V}{C_{max}}$ 

• 
$$r \ge \frac{VV + V}{\tau_{Read}^{c1} C_{max}}$$
  
• and  $\sigma \tau_{read}^{cg1} \ge \frac{1}{2}$ 

• and  $g r_{ImAn} \leq \overline{C_{max}}$ 

• 
$$g \geq \frac{1}{C_{max}\tau_{lmAn}^{cg1}}$$

Min cost: pick smallest r and g.

# $(1+\epsilon)$ -approximation of Time-Cost

#### Cost under time constraint

If you set a cap  $\mathcal{T}$  on time, then you obtain bounds

• 
$$\tau_{Read} \ge \frac{W+V}{C_{max}}$$
  
• and  $\tau_{ImAn} \ge \frac{V}{C_{max}}$ 

So:

• 
$$r\tau_{Read}^{c1} \ge \frac{W+V}{C_{max}}$$
  
•  $r \ge \frac{W+V}{\tau_{Read}^{c1}C_{max}}$   
• and  $g\tau_{ImAn}^{cg1} \ge \frac{V}{C_{max}}$   
•  $g \ge \frac{V}{C_{max}\tau_{ImAn}^{cg1}}$   
Min cost: pick smallest  $r$  and  $g$ .

#### Pareto approximation

Using Papadimitriou and Yannakakis scheme. Pick  $T_{min}$  and  $T_{max}$  and a basis  $1 + \epsilon$ . Return solution for  $T = (1 + \epsilon)^k T_{min}$  for all  $k \in \mathbb{N}; 0 \le k \le \left\lceil \log_{1+\epsilon} \frac{T_{max}}{T_{min}} \right\rceil$ That set is a  $(1 + \epsilon)$  approximation of the Pareto set.



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## Predicting the runtime of pipelined dataflow application is feasible

- Simple bottleneck analysis should work
- Just make sure there are no artificial bubbles in the execution
- Integrates heterogeneous processors gracefully

### Time Cost tradeoff in the cloud

- Once you have a closed formula for the runtime, picking the cheapest machine to finish the application in a given time is easy
- Finding an approximation of the Pareto-Curve is immediate

#### Does low-rank matrices make flowshop easier ?

Here it works becasue we have lots of jobs. Even in the hybrid case ?

#### Dynamic pricing

Spot instances have varying price in time. Can we do a similar analysis with dynamic pricing ?

#### Power and Energy

There are works in pipelined execution with energetic objective. Can we leverage them in practice ?

### More information

Contact : esaule@uncc.edu Visit: http://webpages.uncc.edu/~esaule